## **Mission Layout**

Default layout for SM beta



S SEA MACHINES		Wind 40 30 20 10 20 3	Steadfast     All Stop       Autonomous     All Stop
			Speed: <b>10.4</b> Kts 07
			Heading 320 310 300 290 280
			Position: 07 03.741 N 116 35.301 E
and on Stopped N		1991 - 1991 - 29	Video Radar Status
SP 7 P			Mission Tools
A the man			New Mission Load Mission
man 2	Steadfas		Edit Stored Remove Save
1200 - Carlos Carlos			Map Overlays
			Radar OFF AIS OFF
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			Map Tools
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## Multi Vessel Layout

Default layout collaborative following





## **Create a Mission**

As a Captain I want to create a mission so that I can the launch the mission autonomously.



Wind 40 30 20 10 20 30 40

Steadfast 
Autonomous

				10.4	<sup>RPM:</sup> (ts 07
				Heading 32	0 310 300 290 280
				Position: 07	7 03.741 N
					l6 35.301 E
	JE/ SE	Create New Mission		Video	Radar Status
	r	Select Mission Type:		Mission Tools	
		<ul> <li>Waypoint</li> </ul>		New Mission	Load Mission
	F-S MO	Survey Steadfast		· · · · · · · · · · · · · · · · · · ·	X +
		<ul> <li>Collaborative Following</li> </ul>		Edit Store	d Remove Save
		Patrol	V AD COR SECOND	Map Overlays	
				Radar OFF	
					Camera ON
				Map Tools	
		Car	ncel Save	136	
PORT CAM	ENVD CAM		STBD CAM		
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	1	STA-F			
	a desta a				

Sea Machines



Steadfast ON Autonomous

				Speed: 10.4	RPM: Kts 07	
			and the second sec	Heading	320 310 30	0 290 280
				Position:	07 03.741 116 35.30	1 N 01 E
	- 35/	Create New Mission		Video	Radar	Status
	78	Select Mission Type:		Mission To	ols	
	(Alaman B)	• Waypoint		New Miss	ion Loa	d Mission
		<ul><li>Survey</li><li>Collaborative Following</li></ul>		Edit	tored Remov	/e Save
		Patrol		Map Overl	ays	
		Enter Mission Name:		Radar O	OFF AIS ON Camera	OFF ON
		Cance	el Save	Map Tools		
PORT CAM RECORDING	EVD CAM	AFT CAM RECORDING	STBD CAM O RECORDING		×	
			New York			

5

0

Create New Mission

Select Mission Type:

• Survey

Patrol

Enter Mission Name:

• Waypoint

• Collaborative Following

Cancel

ind <u>40 30 20 10 20 30 40</u>	Autonomou	s	All Stop
	<sup>Speed:</sup>	RPM: Kts 07	
	Heading	320 310 30	0 290 280
	Position:	07 03.74 116 35.3	1 N 01 E
	Video	Radar	Status
	Mission Too	ols	▼
In the New R	New Miss	ion Loa	d Mission
	Edit S	itored Remov	ve Save
	Map Overl	ays	
	Radar	OFF AIS	OFF
		ON Camera	ON
	Map Tools		
Save	3		
STBD CAM O RECORDING		(B)	

Sea Machines

Wind 40 30 20 10 20 30 40

Steadfast 
Autonomous

				10.4 Heading	RPM: Kts 07	0 290 280
				Position: 0	7 03.74 16 35.30	I N 01 E
		Create New Mission		Video	Radar	Status
	72	Select Mission Type:		Mission Tool	5	d Mission
		<ul> <li>Survey</li> <li>Collaborative Following</li> </ul>		Edit Sto	red Remov	re Save
		• Patrol		Map Overlay	/s	
		Enter Mission Name:		Radar Of ARPA O	F AIS	OFF ON
		Cancel	I Save	Map Tools		
PORT CAM		AFT CAM RECORDING	STBD CAM O RECORDING			

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Wind 40 30 20 10 20 30 40

Create New Mis	sion	
Select Mission Type:	0	
<ul> <li>Waypoint</li> </ul>		
<ul> <li>Survey</li> </ul>		

Cancel

• Collaborative Following

• Patrol

Enter Mission Name:

	Steadfas Autonomou	s <b>t ilei</b> is		All Sto	р
	Speed: <b>10.4</b>	Kts	RPM: 07		
	Heading	320	310 30	0 290	280
	Position:	07 (	03.74	1 N	
	<u>á .</u>	116	35.3	01 E	
	Video	Ra	adar	Sta	itus
	Mission To	ols			
	New Miss	sion	Loa	d Miss	ion
	Edit	Stored	Remov	/e	Save
	Map Over	ays			
	Radar	OFF	AIS		OFF
		ON	Camera		ON
/	Map Tools				
$\mid$			-		
			6		
No No					

SEA MACHINES			Wind 40 30 20 10 20	30 40 Steadfast Autonomous Speed: 10.4 Heading	All Stop RPM: (ts 07 310 300 290 280
		Create New Mission		Position: 07 11 Video	7 03.741 N 16 35.301 E Radar Status
		Select Mission Type: • Waypoint • Survey		Mission Tools New Mission	Load Mission
		<ul> <li>Collaborative Following</li> <li>Patrol</li> <li>Enter Mission Name:</li> </ul>		Edit Store Map Overlays Radar OFF	d Remove Save
		New Mission 1	ancel Save	ARPA ON Map Tools	Camera ON
PORT CAM RECORDING	FUD CAM O LCORDING 4 June 10	AFT CAM RECORDING	STBD CAM O.RECORDING		

SEA MACHINES			Wind 40 30 20 10 20	30 40 Steadfast All Stop
				Speed: <b>10.4</b> Kts 07
				Heading 320 310 300 290 280
				Position: 07 03.741 N 116 35.301 E
	JEP A	Create New Mission		Video Radar Status
	77	Select Mission Type:		Mission Tools
	(alange)	<ul> <li>Waypoint</li> </ul>		New Mission Load Mission
		O Survey Steadfast		☆ <b>♀</b> ★ <b>▼</b>
		<ul> <li>Collaborative Following</li> </ul>		Edit Stored Remove Save
		• Patrol		Map Overlays
		Enter Mission Name:		Radar OFF AIS OFF
		New Mission 1		ARPA ON Camera ON
	$\langle \cdot \rangle$			Map Tools
			ancel Save	
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SEA MACHINES		Croate Now Mission	Wind 40 30 20 10 20	30 40 S	teadfast in teadfast itonomous itonomous itonomous itonic	All Stop RPM: 07 310 300 290 280 3.741 N 35.301 E adar Status
	all and a start and a start a	Select Mission Type: • Waypoint			New Mission	Load Mission
		<ul><li>Survey</li><li>Collaborative Following</li></ul>	st D		Edit	Remove Save
		Patrol			Лар Overlays	
		Enter Mission Name: New Mission 1		A	adar OFF	AIS OFF Camera ON
			Cancel Save		lap Tools	
PORT CAM	FUD CAM O CHARDING	AFT CAM RECORDING	STBD CAM O RECORDING			

Wind 40 30 20 10 20 30 40

Create	New	Missi	on
CICALE		1011221	

Select Mission Type:



Steadfas Autonomou	t 💿		All St	ор	
<sup>Speed:</sup>	Kts	<sup>RPM:</sup> <b>07</b>			
Heading	320	310 30	0 29	0 280	
Position:	07 0 116	3.741 35.3(	N )1 E		
Video	Ra	dar	St	tatus	
Mission To	ols				
New Miss	ion	Loa	d Mis	ssion	
Edit	<b>O</b> itored	Remov		Save	
Map Overl	ays				7
Radar	OFF	AIS ( Camera (		OFF	
Map Tools					



Start Plotting a course

Speed: <b>10.4</b>	RP Kts	м: <b>07</b>				
Heading	320 310	300 2	290 280			
Position:	07 03. 116 3	741 N 5.301	E			
Video	Rada	r	Status			
Mission Tools						
New Miss	ion	Load Mission				
Edit	<b>e</b> Sitored	Remove	Save			
Map Overl	ays					
Radar	OFF ON Car	AIS	OFF			
Map Tools						
			A CAR			

Steadfast 💿

Autonomous

All Stop

PORT CAM
 RECORDING

FWD GAM

.



STBD CAM































## Load a Mission

As a Captain I want to load a saved a mission so that I can the launch the mission autonomously. (This scenario makes the assumption you are currently running a mission).



Wind 40 30 20 10 20 30 40

Steadfast ON Autonomous

	120 120 100 5		Speed: <b>10.4</b> Kts	PM: 07
Manual			Position: 07 03 116 3	.741 N 5.301 E
mar sign has	Load Saved Mission		Video Rada	ar Status
Al Jahren and	Select Mission: • Captains Island 2-2-18		Mission Tools New Mission	Load Mission
	<ul> <li>Newport Harbor</li> </ul>		Edit Stored	Remove Save
m ATT	<ul><li>Test Survey 1-15-18</li><li>Harbor Patrol</li></ul>		Map Overlays	
	Learning Demo Collaborative		Radar OFF	
	Simple Follow 1-18-18			amera ON
	Cancel	Load Mission	Map Tools	
PORT CAM Direcording	AFT CAM RECORDING	STBD CAM O RECORDING		

Wind 40 30 20 10 20 30 40

Steadfast Constant Autonomous

Speed: **10.4** Kts 07

				Heading <u>320 310</u>	300 290 280
				Position: 07 03.7 116 35.	41 N 301 E
	- 35/	Load Saved Mission		Video Radar	Status
	Tre	Select Mission:		Mission Tools	
		• Captains Island 2-2-18		New Mission	oad Mission
		<ul> <li>Newport Harbor</li> </ul>		Edit Stored Re	move Save
	7	• Test Survey 1-15-18		Map Overlays	
		<ul> <li>Harbor Patrol</li> <li>Learning Demo Collaborati</li> </ul>	ve	Radar OFF A	
		Simple Follow 1-18-18		ARPA ON Came	ra ON
				Map Tools	-
			Cancel Load Mission		
ORT CAM	FVVD.GAM	AFT CAM RECORDING	STBD CAM O RECORDING		
	3-11-11 2/15				
Wind 40 30 20 10 20 30 40

Steadfast 
Autonomous

Speed: RPM: **10.4** Kts 07

			Heading <u>320 310</u>	300 290 280
			Position: 07 03.7 116 35.	41 N 301 E
- JEPANE	Load Saved Mission		Video Radar	Status
Tri	Select Mission:		Mission Tools	
	Captains Island 2-2-18		New Mission	oad Mission
	Newport Harbor			<b>≮</b> <u></u>
The	Test Survey 1-15-18		Edit Stored Ren	iove Save
	Harbor Patrol			
	Learning Demo Collaboration	ve	Radar OFF AI	S OFF
	Simple Follow 1-18-18		ARPA ON Camer	a ON
			Map Tools	
		Cancel Load Mission	362	
A dimension		Ser -		

Wind 40 30 20 10 20 30 40

Steadfast 
Autonomous

Speed: RPM: **10.4** Kts 07

				Heading 320	310 300 290 280
				Position: 07 11	03.741 N 6 35.301 E
		Load Saved Mission		Video	Radar Status
	72	Select Mission:		Mission Tools New Mission	Load Mission
		Newport Harbor     Test Survey 1-15-18		Edit Stored	Remove Save
		<ul> <li>Harbor Patrol</li> <li>Learning Demo Collaborat</li> </ul>	ive	Map Overlays	AIS OFF
		Simple Follow 1-18-18		ARPA ON	Camera ON
			Cancel Load Mission		
PORT CAM © RECORDING	EVD CAM O Sacording	AFT CAM RECORDING	STBD CAM O RECORDING		
			Contrar Internet		

Wind 40 30 20 10 20 30 40

Steadfast 
Autonomous

Speed: RPM: **10.4** Kts 07

Manual		Heading <u>320 310 300 290 280</u> Position: 07 03.741 N 116 35.301 E	
sances 55 pt	Load Saved Mission	Video Radar Status	
	Select Mission: • Captains Island 2-2-18 • Newport Harbor • Test Survey 1-15-18 • Harbor Patrol • Learning Demo Collaborative • Simple Follow 1-18-18	Mission Tools          New Mission       Load Mission         Image: Constraint of the second secon	
PORT CAM © RECORDING	Cancel Load Mission          AFT CAM       STBD CAM         RECORDING       ORECORDING	Map Tools	

Wind 40 30 20 10 20 30 40

Steadfast 💿

Speed: **10.4** Kts 07

				Heading P2	210 200 200 280
				Position: 07	03.741 N
					6 35.301 E
	- 35/	Load Saved Mission	216 236	Video	Radar Status
	78	Select Mission:		Mission Tools	
	1 marting	• Captains Island 2-2-18		New Mission	Load Mission
		Newport Harbor		<b>\$</b>	* -
	The Carlos and	• Test Survey 1-15-18		Edit Stored	Remove Save
		Harbor Patrol		Map Overlays	
		Learning Demo Collabora	ative	Radar OFF	
		Simple Follow 1-18-18			Camera ON
				Map Tools	
			Cancel Load Mission		
5 /				R	
PORT CAM	TENVID GAM		STBD CAM		
RECORDING	O Graninale	RECORDING	ORECORDING		
			and the second s		

Wind 40 30 20 10 20 30 40

Steadfast Constant Autonomous

Speed: RPM: **10.4** Kts 07

280

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					Heading 520	510 500	290 280
					Position: 07 ( 116	)3.741 35.301	N 1 E
	-35/	Load Saved Mission		456 1825	Video	adar	Status
	72	Select Mission:		5-2-	Mission Tools	Load	Mission
		<ul> <li>Captains Island 2-2-18</li> <li>Newport Harbor</li> </ul>				*	
	T	<ul> <li>Test Survey 1-15-18</li> <li>Harbor Patrol</li> </ul>			Map Overlays	Remove	Save
		<ul> <li>Learning Demo Collaborati</li> <li>Simple Follow 1-18-18</li> </ul>	ve	106 213	Radar OFF	AIS Camera	OFF
					Map Tools		
			Cancel Load Mission		36		
PORT CAM © RECORDING		AFT CAM RECORDING	STBD CAM O RECORDING				
	And the second s						







# Stop (Pause) / Resume Mission

As a Captain I want to stop a mission so I can manually make adjustments then resume the mission without having to abort or start over.









#### **Abort Mission**

As a Captain I want to abort a mission that is currently deployed so I can manually control the vessel and have to need to reengage with a mission.







#### Read only Indicators to show what mode the vessel is in

As a Captain need to visually see what mode the vessel is in so I have a visual cue of the status, these modes are "Manual", "Remote" and a "Autonomous".



### **Read only Indicators to show course details**

As a Captain I need to visually see the current course details so I can always be aware of the vessels physical status. These include:

- RPM KTS Pitch
- PitchRoll
- Speed
- Wind
- Fuel

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### Read only Indicators to show my the status of the UI signal connection to the vessel

As a Captain I need to visually see the current connection status and strength to be able to see if there is an issue that may need to be addressed  $\mathcal{F}$ 

#### Mission Timeline visualization and interaction

As a Captain I need to visually see the current mission and timeline and be able to interact to see where is started from to the live status or completed status. Think DVR TiVo



### Name and save waypoints

As a Captain I want to be able to save and name a waypoint so I can easily retrieve it later and simply add it to a mission (think favorites or bookmarks)









Waypoint 3		
41.4901°		71.3128°
	Cancel	Save

Η	or	ne	
٦	OI	ne	

41.4901°		71.3128°
----------	--	----------

#### Save and store this waypoint for future use

Cancel	Save
--------	------



## Load saved waypoints

As a Captain I want to be able to load a previously saved waypoint so I can easily retrieve it and add it to a mission (think favorites or bookmarks)







 $\bigcirc$ 

Cancel	Load
--------	------
○○● Home

Cancel	Load
--------	------



## **Collaborative Following**

As a Captain I need to create a mission so that I can manually control one vessel while another vessel autonomously follows my lead





Cancel	Save
--------	------

Chlaborative Following

Cancel	Save
--------	------

# Waypoint Collaborative Following

New Mission 1

Cancel	Save	
		J.

O Orca

Cancel	Save
--------	------

#### O Orca

#### • The Black Pearl

Cancel Save













#### The Black Pearl

Status: Lead Ship Manual Longitude Vector Distance from Orca (Following): Depth





# Show / Hide Tools

New

As a Captain I want to hide the tools on my screen so I can have more real-estate for on my screen for viewing the map

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#### **Tools Defined**

New

As a Captain I want to understand the use for all the buttons in the "Tools" area so I can easily navigate the creating of a mission "Remove" "Undo" "Return"







×







### Video

New

As a Captain I want to view the video feeds (3) on my vessel so I can visually follow my mission and have the option to have a draggable window available on the main screen

## Video Settings

New

As a Captain I want to adjust the settings on my video feeds individually or all at one time so I can save time and space on my display







 $\square$ 



















#### **Video Feed Selection**

New

As a Captain I want to select between the 3 video feeds in the popup window on my vessel so I can quickly select my preferred view




























## AIS / Radar Toggle On – Off Buttons

As a Captain I want to be able to quickly turn off and on map features so I can easily see my preferred view between AIS and Radar or both  $\mathcal{F}$ 



### Show all status

New

As a Captain I want to view all my status options in a full screen setting so that I can see all settings quickly when needed and be able so hide them to view my main screen







Close









 Engine 1 Rpm | Water Temp | Pressure

Engine 2 Rpm | Water Temp | Pressure

> Rudder 1 Position

Rudder 2 Position

Fuel Tank 1 Level

Fuel Tank 2 Level

Battery 1 Voltage

Battery 2 Voltage

Batter House Voltage

•



Alarms or Status	Buttons	Value / Gauges
Port Engine Alarm	Port Engine Start	
Stbd Engine Alarm	Port Engine Shutdown	Engine 1 Rpm
Bilge 1 Alarm	Stbd Engine Start	Engine 2 Rpm
Bilge 2 Alarm	Stdb Engine Shutdown	Rudder 1 Position
Fire Alarm	Bilge 1 ON/Off	Rudder 2 Position
Security Alarm	Bilge 2 ON/OFF	Fuel Tank 1 Level
	Nav Lights ON/OFF	Fuel Tank 2 Level
Aux 1	Horn	Battery Voltage 1
Aux 2	Mast Light 1	Battery Voltage 2
Aux 3	Mast Light 2	Batter Voltage House
Aux 4	Mast light 3	Engine 1 Water Temp
Aux 5	Strobe Work Light	Engine 2 Water Temp
Aux 6	GPS On/Off	Engine 1 Gear Temp
Aux 7	Ais On/Off	Engine 2 Gear Temp
Aux 8	Vsat On/Off	Engine 1 Pressure
	Radio On/Off	Engine 2 Pressure
	Cam 1 On/Off	
	Cam 2 On/off	
	Cam 3 ON/off	
	Aux 1 On/Off	
	Aux 2 On/Off	
	Aux 3 On/Off	









Undo





**Mission Timeline** 

6

Minutes Hours Days



Undo

Save



Minutes Hours Days



## **Collaborative Following Edit configuration**

As a Captain I need to edit the vessel configuration so that I can choose what vessel is the lead and what vessel is autonomous









Remove







Orca Remove Edit Remove Edit

Orca: Manual, Lead Autonomous, following

Type Vessel Name

Cancel Add Vessel



Remove

Drca Remove Edit Remove Edit



Type Vessel Name



Remove

## $\mathcal{F}$

Add / Edit Vessels	Cancel	Save
--------------------	--------	------

## **Collaborative Following Add Vessel**

As a Captain I need to add a Vessel to my system so I can select it as one of my choices for a mission







## Orca Orca Substant of the second secon

Add / Edit Vessels	Cancel	Save
--------------------	--------	------



## O Orca O Orca O





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Cancel	Add Vessel
--------	------------



۲ Add Vessel

Cancel



## Orca Orca Orca Add / Edit Vessels...







# Orca Orca SM Versel 8 Add / Edit Vessels...



## **Collaborative Following Remove Vessel**

As a Captain I need to remove a Vessel from my system so It can no longer be selected for any mission



			B
	Remove	Edit	
	Remove	Edit	
Orca: Manual, Lead Autonomous, following	Change Vess	el hierarchy	

Type Vessel Name		
	Cancel	Add Vessel




Type Vessel Name		
	Cancel	Add Vessel













CHART	MISSION	CONFIG	STATUS	SENSORS	VIDEO	DATA	PAYLOAD











CHART	MISSION	CONFIG	STATUS	SENSORS	VIDEO	DATA	PAYLOAD



















CHART	MISSION	CONFIG	STATUS	SENSORS	VIDEO	DATA	PAYLOA
ΤΑΙ	_os	MANUAL	REMOTE   AU	то			

CAMERA V

14:23 :35





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Are these buttons even necessary, wouldn't the UI suggest that if you engage or deploy a mission manual is off?

For Remote wouldn't the same be true, if I engage the remote (a physical device) it would simply take control?

So my question is are these not simply indicators rather than actions engaged through the UI?

What gages would we like to see?

What style could be produce?

Can this screen be modified or customized or Hide and Show what the user prefers visually?

Mission timeline, how far back can this go? Hours, Day's and so on. How would this interaction be shown and is it possible?

B





# **Context menu alternative 1**

On screen tools with contextual cues



























hJ



Save	
Cancel	
Deploy	
Waypoint 1: LAT: 51* 05*′.45 N LON: 003* 10′.14 E	\$
Waypoint 2: LAT: 53* 07*'.49 N LON: 002* 14'.19 E	<b>X</b>
Enter Name	45
Enter Lat, Lon	

Save

Cancel





	N E
Waypoint 2: LAT: 53* 07*'.49 LON: 002* 14'.19	N E
Home	N
Enter Lat, Lo	on A
Cancel	Save



Save
Cancel
Deploy

Waypoint 1: X   LAT: 51* 05*'.45 N X   LON: 003* 10'.14 E X
Waypoint 2: LAT: 53* 07*'.49 N LON: 002* 14'.19 E
Home
Lat: 51 Lon: 51, 32
Cancel Save



Save
Cancel
Deploy

Waypoint 1: X   LAT: 51* 05*'.45 N Image: Compare the second seco
Waypoint 2: LAT: 53* 07*'.49 N LON: 002* 14'.19 E
Home
Lat: 51 Lon: 51, 32
Cancel Save
45





Waypoint 1: LAT: 51* 05*'.45 N LON: 003* 10'.14 E				
Home: LAT: 53* 07*'.49 N LON: 002* 14'.19 E	<b>×</b>			
Home				
Lat: 51 Lon: 5	51, 32			
Cancel	Save			





<b>×</b>
<b>X</b>









# **Touchscreen Gestures**

Тар

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Pinch



# Windows Touchscreen Gestures

GESTURE	WINDOWS USAGE	GESTURE ACTION	ACTION (◯= finger down    ᠿ= finger up)	Single Contact	Multi Contact
Tap / Double Tap	Click / Double Click			*	$\rightarrow$
Panning with Inertia	Scrolling	Drag 1 or 2 fingers up and down			×
Selection / Drag (left to right with one finger)	Mouse Drag / Selection	Drag one finger left / right	+ +	*	×
Press and Tap	Right-click	Press on target and tap using a second finger	En En En		*
Zoom	Zoom (defaults to CTRL key + Scroll wheel)	Move two fingers apart / toward each other			×
Rotate	No system default unless handled by Application (using WM_GESTURE API)	Move two fingers in opposing directions -or- Use one finger to pivot around another	-or- 55-		×
Two-Finger Tap	N/A – Exposed through Gesture API, used by Application discretion.	Tap two fingers at the same time (where the target is the midpoint between the fingers)			×
Press and Hold	Right-click	Press, wait for blue ring animation to complete, then release	press hold release	*	×
Flicks	Default: Pan up/ Pan Down/ Back, and Forward	Make quick drag gestures in the desired direction		*	×

